

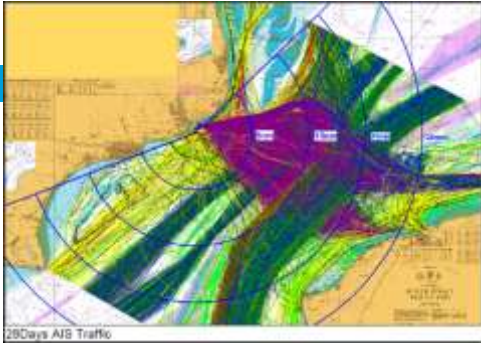


# eLoran Results in the UK & US

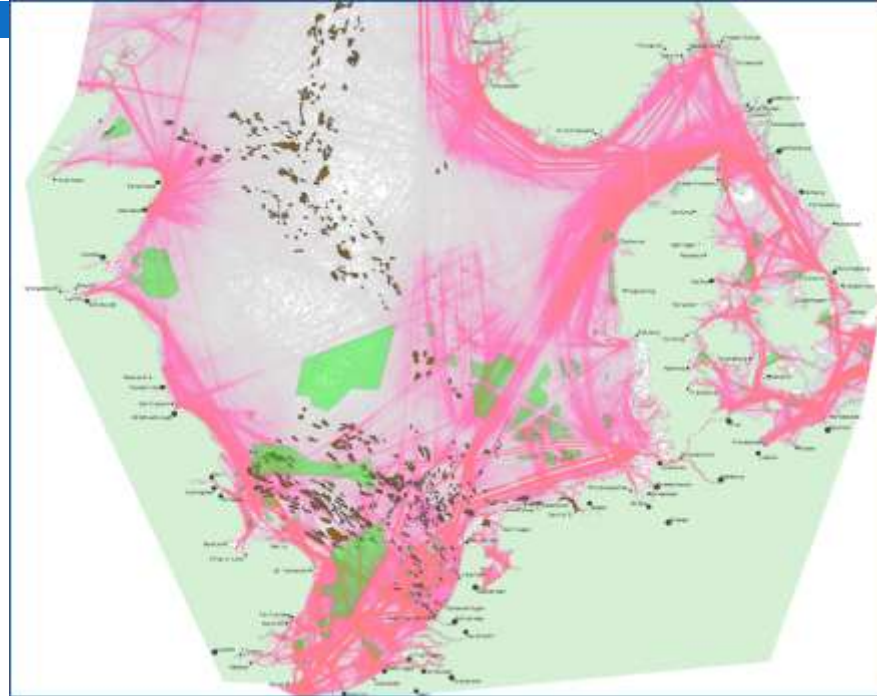
OCTOBER 2018

Melaha Conference - Cairo

# Maritime need for Resilient PNT



Risk of maritime navigation around the UK is growing



# GPS vulnerability to interference



THV Galatea



*Jammer of less than 1 milliWatt:*

- False positions, and velocities
- Autopilot may turn vessel
- But no alarms!

*With a little more jammer power:*

- Electronic Chart Displays
- Autopilot
- Automatic Identification System
- Differential GPS
- Satellite voice and data comms
- Maritime distress safety system

*plus ...*

**Ship's Radar & Gyrocompass**



# Problem

GPS is everywhere



Synchronized,  
Precise Time,  
Frequency,  
Phase

Precise Positioning  
& Navigation

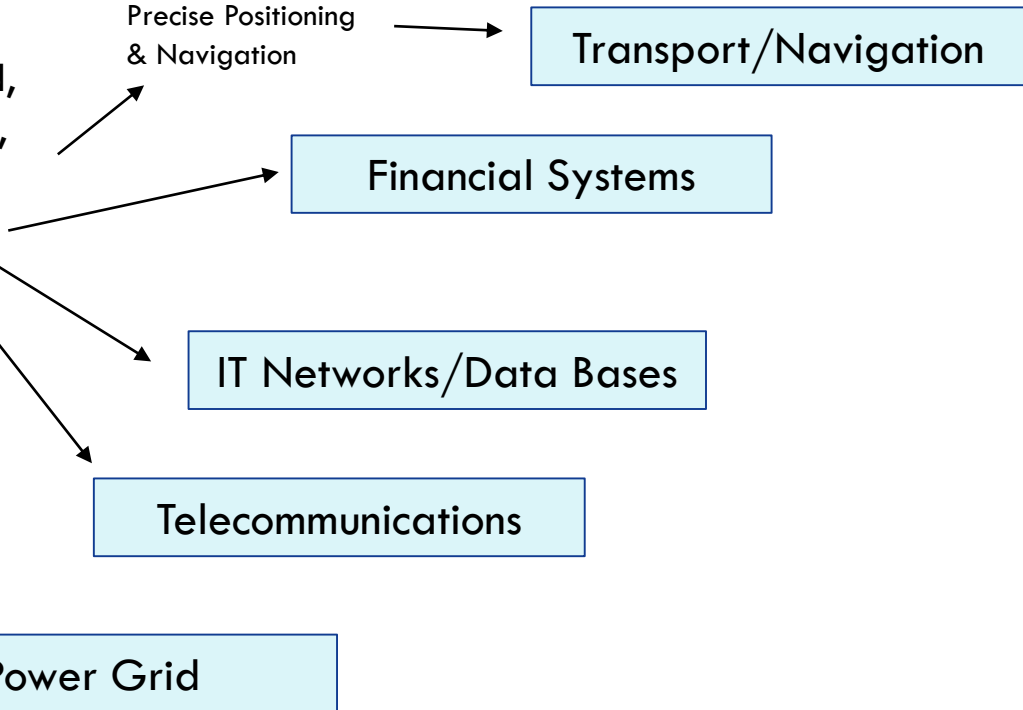
Transport/Navigation

Financial Systems

IT Networks/Data Bases

Telecommunications

Power Grid



# Problem

GPS is everywhere  
“Single Point of Failure” - DHS



Synchronized,  
Precise Time,  
Frequency,  
Phase

Precise Positioning  
& Navigation

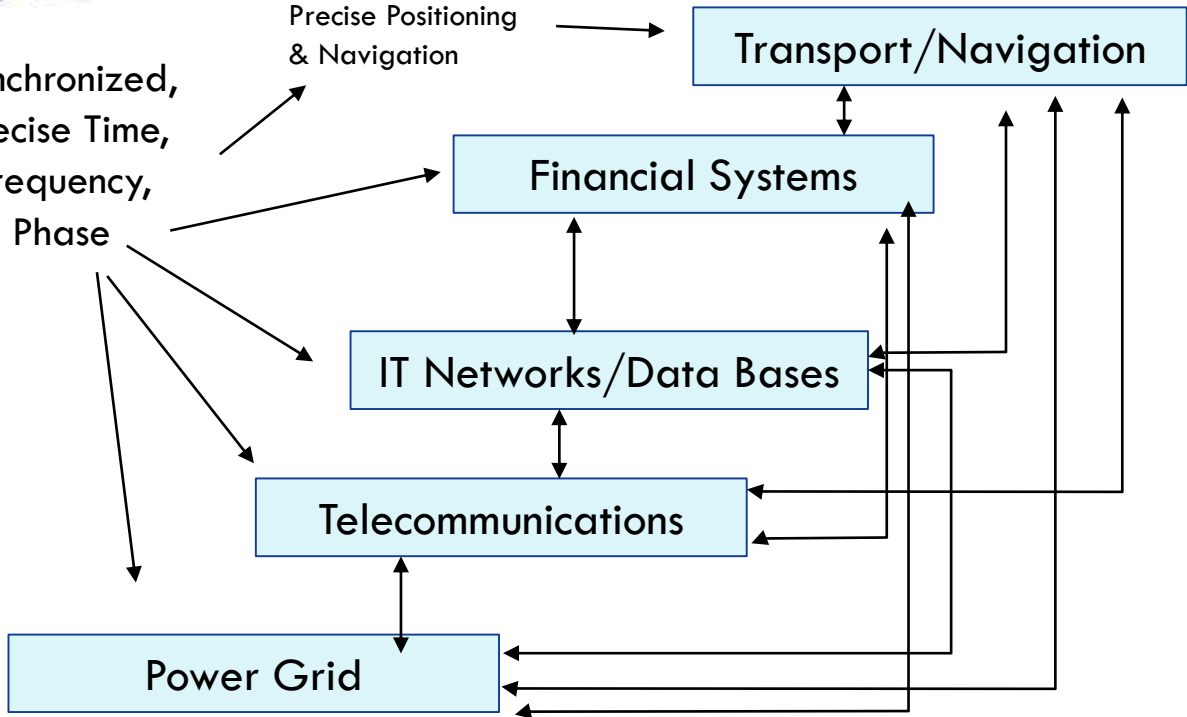
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Power Grid



Vice President Pence Hosts National Space Council



<https://www.youtube.com/watch?v=9zW2bLJXkRU>

# What to Do?

- Protect – GPS Signals
- Toughen – Users & Equipment
- Augment – w/other signals & sources



# What to Do?



- Protect – GPS Signals
  - Interference detection
  - Enforcement





# What to Do?



- Toughen – Users & Equipment
  - Anti-jam, anti-spoof
  - Standards, requirements, costs



Radio Equipment Directive  
– GNSS Receivers

# What to Do?



- **Augment** — w/other signals & sources
  - Five major studies — “eLoran is best/only solution”
  - US Govt Announcement 2008 — “Will build eLoran”
  - US Govt Announcement 2015 — “Will build eLoran”

2018 - \$10M for GPS backup Technology Demonstration

# eLoran – low cost, high performance

- Terrestrial, high-power, low-frequency system
- Modern digital technology
- No common mode of failure with GPS
- Plug-and-Play Compatible GPS augmentation
- Accurate positioning
- Precise UTC timing and frequency
- Robust data communications
- Autonomous operation



NASA Provides Coverage of the National Space Council Meeting

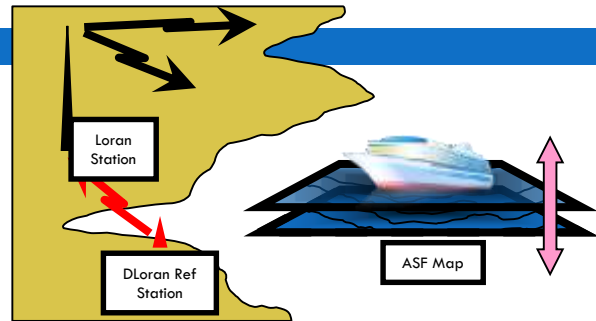


<https://www.youtube.com/watch?v=wbJMExW9Rvo>

# eLoran UK Initial Operational Capability

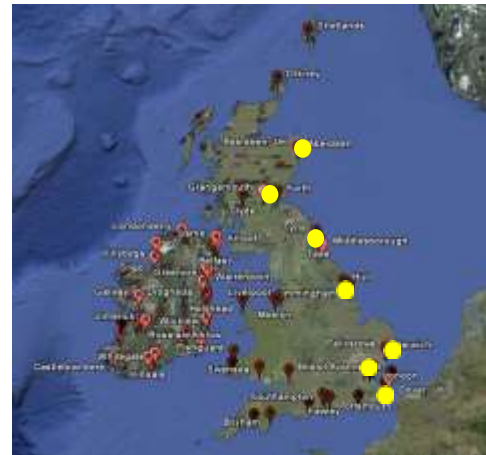


UK maritime eLoran  
IOC declared on  
31 October 2014



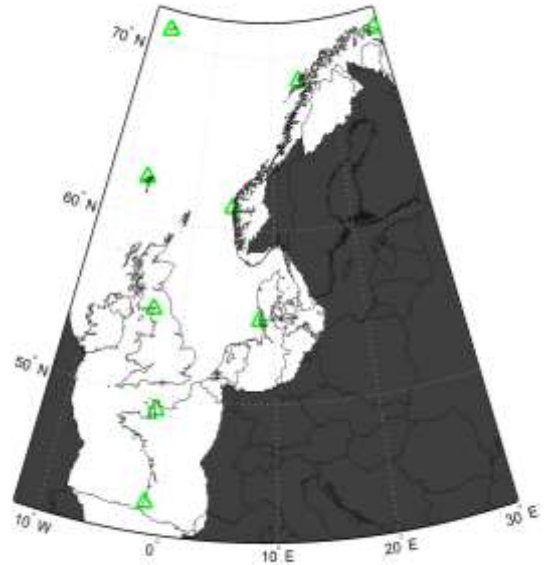
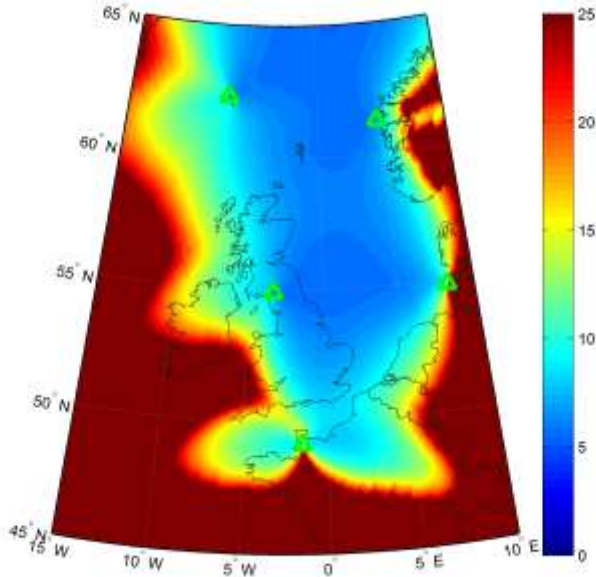
Differential operation

- 7 major UK east coast ports



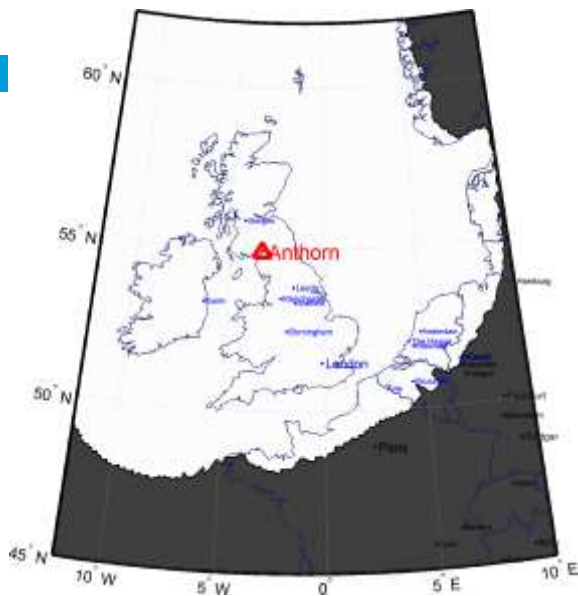
# eLoran IOC coverage

Position accuracy capability (metres)



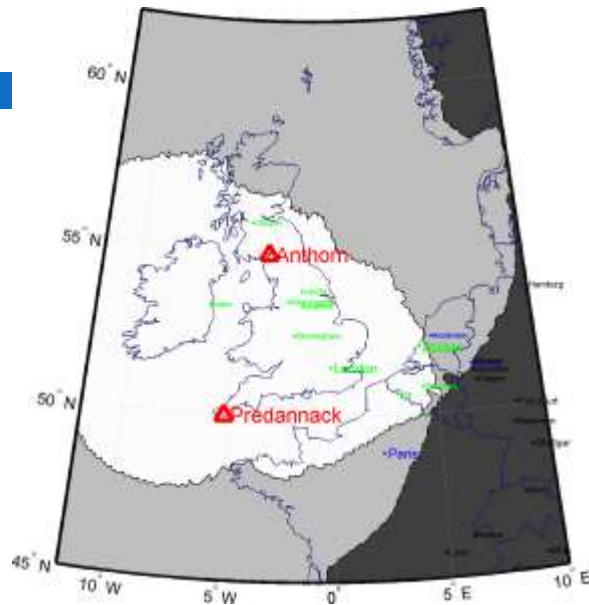
Indoor coverage of eLoran 500ns timing accuracy

# UK-only Timing & Data Capability



UTC Timing from UK Anthorn  
Transmitter alone: 500ns, indoors

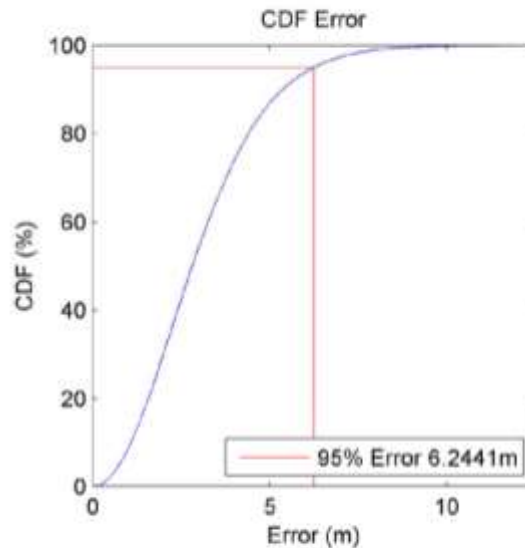
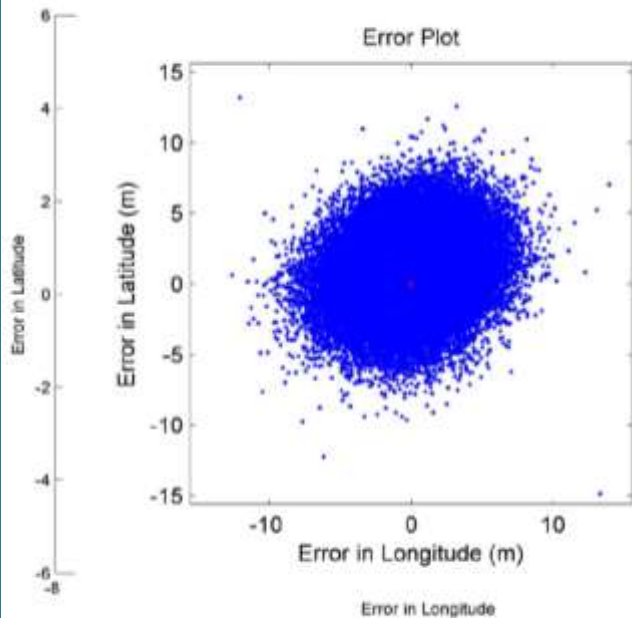
**Single Tx Timing & Data capability**



With a 2<sup>nd</sup> UK permanent  
transmitter (100kW) installed in  
Cornwall

**Robust UTC Timing & Data  
capability**

# Humber Site – Location accuracy





# Summary, all Locations

Differential eLoran Station	Predicted Horiz. Accuracy (95%)	Measured Horiz. Accuracy (95%)	Difference vs Model
Harwich	8.90 m	6.59 m	25.9 % better
Dover	10.20 m	6.87 m	32.6% better
Sheerness	9.30 m	7.78 m	16.3% better
Middlesbrough	5.80 m	No data yet	tbd
Leith	8.40 m	7.14m	15.0% better
Aberdeen*	7.20 m	7.33m	1.8% worse
Humber*	6.40 m	6.24 m	2.5% better

\* At Aberdeen and Humber the antennas are located on the wall of a building and thus have less elevation than the other sites. It should also be noted that the model was based on previous performance attained using an H-field antenna

# eLoran Initial Operational Capability in the United Kingdom – First results

Gerald Offermans, Erik Ahmestessen, Stephen Bartlett, Charles Schae, Andrei Grobner, *UrsaNac, Inc.*  
Martin Bramby, Paul Williams, Chris Hargreaves, *General Lighthouse Authorities of the UK and Ireland*

## BIOGRAPHIES

Dr. Gerald Offermans is Senior Research Scientist of the UrsaNac LFBU engaged in various R&D project work and product development. He supports customers and operations in the European, Middle East, and Africa (EMEA) region from UrsaNac's office in Belgium. Dr. Offermans is one of the co-developers of the Eurofox data shared concept deployed at Loran installation worldwide. Dr. Offermans received his PhD, with honours, and Master's Degree in Electrical Engineering from the Delft University of Technology.

Erik Ahmestessen is Vice President of LF Business Development at UrsaNac. He is responsible for leading the Low Frequency Business Unit (LFBU) in business development, and also provides technical and operational expertise with LF Business Unit systems, services, and products.

Steve Bartlett is Vice President of Operations for the UrsaNac LFBU. He is responsible for all aspects of business operations including manufacturing, engineering, quality control, program management, and project delivery. Steve served as an active duty officer in the U.S. Coast Guard and retired from the U.S. Coast Guard Reserve. He earned his BS in Electrical Engineering from Northeastern University and an MS in Electrical Engineering from North Carolina State University.

Charles Schae is co-owner and President of UrsaNac, Inc. He champions providing Low Frequency Alternative Positioning, Navigation, Time and Frequency, and Data solutions for "sky-challenged" users. He served in the U.S. Coast Guard, where his expertise included radio navigation systems, and was the first Commanding Officer of the Coast Guard's Loran Support Unit. He holds Masters Degrees in Electrical Engineering, Engineering Management, and Business Administration. He is a Fellow of the Royal Institute of Navigation.

Andrei Grobner is Principal Engineer at UrsaNac, Inc. and is responsible for the design of new products for LF systems and eLoran user equipment technology. He received BS and MS degrees in Radioelectronics Engineering from Moscow Aviation Institute. He worked at the same Institute as Senior Research Engineer and later as Chief of Receivers Laboratory. Mr. Grobner holds patents pertaining to the use of magnetic loop antenna

for Loran and has authored several papers on the subject.

Martin Bramby is the Manager of the Research and Radionavigation Directorate of the General Lighthouse Authorities of the UK and Ireland. He is responsible for the delivery of its project portfolio in research and development in such technical areas as AIS, eLoran, e-Navigation, GNSS and Lights. He is a Fellow of the Royal Institute of Navigation, and holds memberships of the Institute of Engineering & Technology and the US Institute of Navigation. He is also a member of the International Marine Aids to Navigation and Lighthouses Authorities' (IALA) Aids to Navigation Management Committee.

Dr. Paul Williams is a Principal Development Engineer with the Research and Radionavigation Directorate of the General Lighthouse Authorities of the UK and Ireland, based at Trinity House in Harwich, England. He is currently the technical lead of the GLA's eLoran Work Programme. The work involves planning the GLA's maritime eLoran trials and work on a wide range of eLoran related projects. He holds BSc and PhD degrees in Electronic Engineering from the University of Wales, is a Chartered Engineer, a Fellow of the Royal Institute of Navigation, and is chairman of the Radio Technical Commission for Maritime Services Special Committee 117 on Standards for Enhanced Loran (eLoran) Systems.

Chris Hargreaves is a Research and Development Engineer with the Research and Radionavigation Directorate of The General Lighthouse Authorities of the UK and Ireland, based at Trinity House in Harwich, England. His work is focused on the GLA's eLoran project in particular measurement trials, software development and data analysis. He holds an MSc degree in Mathematics and Physics from the University of Durham, and an MSc in Navigation Technology at the University of Nottingham and is a member of the Institute of Navigation and the Royal Institute of Navigation.

## ABSTRACT

There is an increasing awareness in the Maritime world that no single system can provide Position, Navigation, and Time (PNT) resiliently under all circumstances. At this moment GPS (with augmentation) is used on most commercial vessels, and in many cases integrated into systems we did not expect would need or use GPS derived

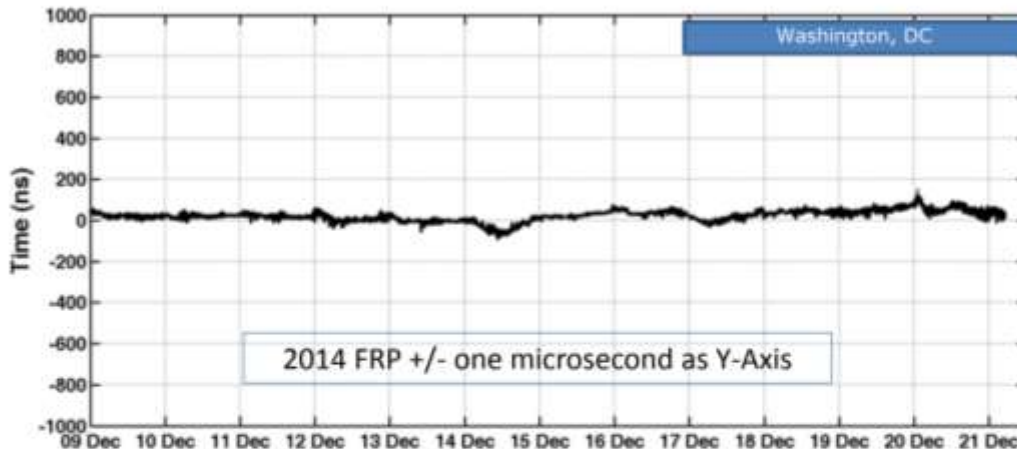
ION Paper

50ns achieved outside

# Work in the United States (example)



Wildwood, NJ to Washington, DC (USNO) User Receiver



Period: December 2015  
Distance to XMTR: 120 miles  
Mean: 22.9 ns  
STD: 26.1 ns  
Max: 147.0 ns  
Min: -90.0 ns

[www.Ursanav.com](http://www.Ursanav.com)



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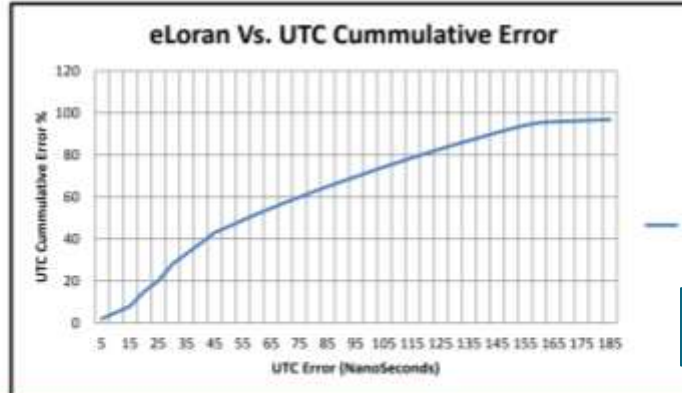
# Work in the United States - Summary



## eLoran CRADA Executive Summary



- ❑ **Without** differential corrections or augmentations, eLoran results have easily demonstrated the ability to meet the (+/-) **one microsecond** timing synchronization requirement proposed in the 2014 Federal Radionavigation Plan (FRP)
- ❑ **Without** differential corrections or augmentations, eLoran results within a **500 mile** range of the test transmitter location have demonstrated (+/-) **500 nanoseconds** synchronization to UTC
- ❑ **Without** differential corrections or augmentations, **95%** of all data collected was **within 156 Nanoseconds** of UTC



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# Work in the United States - Summary



## eLoran CRADA Executive Summary



- ❑ **With differential corrections** applied at certain locations in the vicinity of a Differential eLoran Reference Station, eLoran demonstrated time synchronization to UTC well within **100 nanoseconds**
- ❑ eLoran was proven in field trials to be a **successful backup** to GPS timing in a Wide Area Multilateration (**WAM**) aviation application, providing **equivalent performance** to GPS
- ❑ **Additional aviation testing** is ongoing, with plans underway to demonstrate precise time synchronization, Loran Data Channel (LDC) communication, and compass (heading) applications in Unmanned Aerial Vehicles and General Aviation aircraft **in January 2017**
- ❑ eLoran in **Smart Grid application** Proofs-of-Concept are planned for **Feb/March 2017**

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# Portable Capability



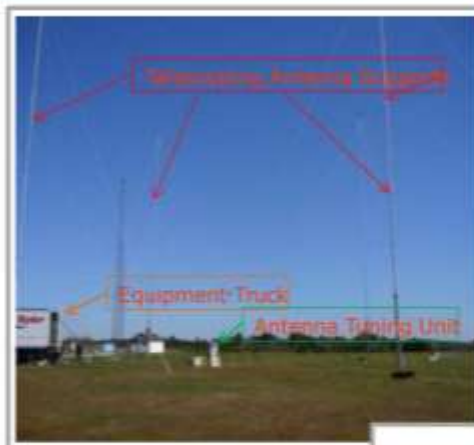
## "Triple-T" Solutions

### "Triple-T"

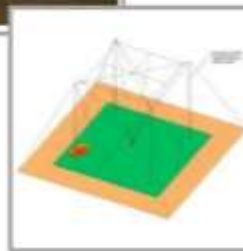
- Temporary
- Tactical
- Transportable

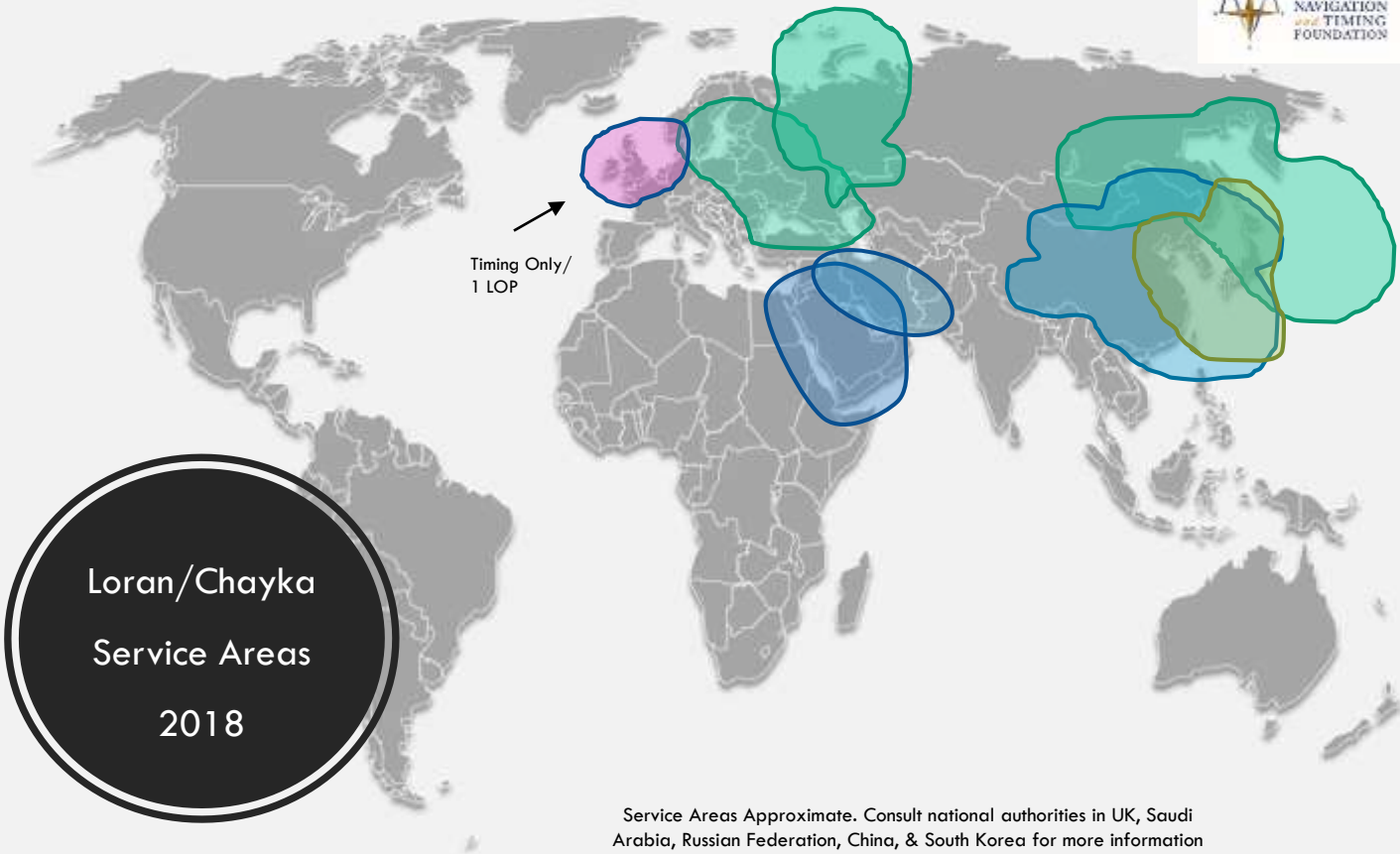
### Field Tested

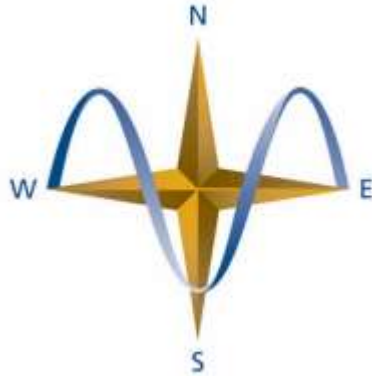
- 4-6 hours setup
- ~ 140 mile range
- 70' x 70' x 70' Inverted Pyramid
- "Box" truck mimics CONEX
- Successfully deployed three times



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NAVIGATION  
*and* TIMING  
FOUNDATION

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